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IN THE CLAIMS

1-24. Cancelled

25. (Currently amended) ~~A spinning-wheel bonus~~ An electromechanical

indicator comprising:

~~a wheel-shaped indicator~~ rotary body having an axis of rotation and which is provided with a plurality of segments radiating from said axis of rotation, wherein said segments are associated with at least two different indicia; and

a motor coupled to said rotary body such that ~~said wheel-shaped indicator~~ rotary body is adapted for a rotating mode and a stationary mode about said axis of rotation;

a pointer associated with ~~said wheel-shaped indicator~~ rotary body to point to a predetermined segment of one of said plurality of segments when said ~~wheel-shaped indicator~~ rotary body is in said stationary mode; and

a segment detector for detecting a rotary position of each of said plurality of segments.

~~a controller receptive to a monetary input and operative to control said rotating mode and said stationary mode of said wheel-shaped indicator such that said pointer is aligned with a predetermined segment of said wheel-shaped indicator.~~

26. (Currently amended) ~~The spinning-wheel bonus~~ electromechanical

indicator as recited in Claim 25, wherein said at least two different indicia

comprise two different numeric values ~~displayed within two different segments of~~
~~said wheel-shaped indicator.~~

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27. (Currently amended) The ~~spinning wheel bonus~~ electromechanical indicator as recited in Claim 25, wherein said at least two different indicia comprise two different symbolic values displayed ~~within two different segments of said wheel-shaped indicator.~~

28. (Currently amended) The ~~spinning wheel bonus~~ electromechanical indicator as recited in Claim 25, wherein said ~~wheel-shaped indicator~~ rotary body is in a form of a ~~mechanical wheel on a game unit.~~

29. (Currently amended) The ~~spinning wheel bonus~~ electromechanical indicator as recited in Claim 25, wherein said ~~mechanical wheel is driven by~~ motor is a stepper motor.

30. (Currently amended) The ~~spinning wheel bonus~~ electromechanical indicator as recited in Claim 29, wherein said ~~motor is a stepper motor~~ further comprising a stepper motor controller coupled to said stepper motor.

31. (Currently amended) The ~~spinning wheel bonus~~ electromechanical indicator as recited in Claim 25, wherein said motor ~~29, wherein said motor~~ is a servo motor.

32. (Currently amended) The ~~spinning wheel~~ electromechanical Indicator ~~system~~ as recited in Claim 25, wherein said predetermined segment is randomly chosen.

33. (Currently amended) The ~~spinning wheel~~ electromechanical indicator system as recited in Claim 25, wherein said ~~controller is~~ further comprising a

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controller coupled to said segment detector and said motor ~~a position detection mechanism~~ for controlling said rotating mode and said stationary mode.

34. (Currently amended) An indicator ~~wheel~~ system comprising:

~~an a-wheel-shaped~~ indicator having an axis of rotation and defining a major surface, said ~~wheel-shaped~~ indicator being provided with a plurality of segments associated with said major surface and radiating from said axis of rotation, wherein said plurality of segments are associated with at least two different indicia;

a stepper motor for selectively providing ~~rotary~~ rotary motion to said ~~wheel shaped~~ indicator to provide a rotating mode and a stationary mode with respect to said axis of rotation;

an optical position sensor associated with said ~~wheel-shaped~~ indicator to determine ~~at least one a~~ position of each of said plurality of segments ~~said wheel shaped indicator~~; and

a pointer associated with said ~~wheel-shaped~~ indicator to point to ~~one a~~ predetermined segment of said plurality of segments when said ~~wheel-shaped~~ indicator is in said stationary mode.

35. (Currently amended) ~~An~~ The indicator ~~wheel~~ system as recited in claim 34 wherein said ~~wheel-shaped~~ indicator is substantially a circular disk, and wherein said major surface is a first major surface, said circular disk further having a second major surface substantially parallel to said first major surface.

36. (Currently amended) ~~An~~ The indicator ~~wheel~~ system as recited in claim 34

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35 wherein said plurality of segments are provided on said first major surface.

37. (Currently amended) ~~An~~ The indicator wheel system as recited in claim 34 further comprising a stepper motor controller coupled to said stepper motor.

38. (Currently amended) ~~An~~ The indicator wheel system as recited in claim 34 further comprising control circuitry coupled, directly or indirectly, to said stepper motor and said optical position sensor.

39. (Currently amended) ~~An~~ The indicator wheel system as recited in claim 38 wherein said control circuitry includes a microprocessor.

40. (Currently amended) ~~An~~ The indicator wheel system as recited in claim 39 wherein an output signal of said optical position sensor can provide segment position information to said control circuitry ~~said at least one position of said wheel-shaped indicator to said control circuitry to be used with respect to at least one control of said stepper motor by said control system.~~

41. (New) An indicator comprising:

rotary indicator means provided with a plurality of segments radiating from an axis of rotation;

motor means for rotating said rotary indicator means around said axis of rotation;

segment position detection means for detecting each segment of said plurality of segments; and

controller means coupled to said motor means and said segment position

detection means for selectively rotating said rotary indicator means and stopping

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said rotary indicator means on a predetermined segment of said rotary indicator means.

42. (New) A method for indicating a predetermined result comprising:

rotating an indicator around an axis of rotation, said indicator being provided with a plurality of segments radiating from said axis of rotation;

detecting a plurality of rotary positions of said indicator during a rotation of said indicator; and

stopping the rotation of said indicator at a selected segment to indicate a predetermined result indicated by said selected segment.

43. (new) An electromechanical indicator as recited in claim 25 wherein said plurality of segments are all of the segments of said rotary body.

44. (new) An indicator system as recited in claim 34 wherein said plurality of segments are all of the segments associated with said major surface.

45. (new) An indicator as recited in claim 41 wherein said plurality of segments are all of the segments of said rotary indicator means.

46. (new) An indicator as recited in claim 42 wherein said plurality of segments are all of the segments of said indicator.